

Multivariable Calculus (Math 53) MT2 Review: Max/min, Lagrange multipliers, change of variables, V-fields and line integrals.

Extreme Value Thm - If region  $D$  is closed and bounded and  $f$  is continuous,  $f$  has a minimum and maximum on  $D$ .

- To find min/max,
- Find critical points of  $f$  on interior of  $D$  (set  $f_x = f_y = 0$ )
  - Find min/max of the restriction of  $f$  to the boundary of  $D$  ( $g=k$ ) (parametrize  $x$  and  $y$  in terms of  $t$ , plug into equation of boundary, find where  $f'_t(t) = 0$ )
  - Evaluate function at points in interior (1) and on boundary (2) to see which is the max and which the min

2nd Derivative Test

states that given a twice-differentiable function  $f(x,y)$ , let

$$D = \begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix} \text{ evaluated at point } P(x_0, y_0)$$

IF  $(D > 0 \wedge \begin{cases} f_{xx} > 0 & \text{minimum} \\ f_{xx} < 0 & \text{maximum} \end{cases})$  ELSE IF  $(D < 0 \Rightarrow \text{saddle point})$  ELSE  $\Rightarrow$  inconclusive

Lagrange Multipliers

To find max/min of  $f$  subject to constraint  $g=k$ , where  $g(x,y,z)=k$  is the equation describing the boundary, it is sufficient to find the solution to the system of equations

$$\nabla f = \lambda \nabla g \text{ and } g=k, \text{ assuming } \nabla g \neq 0 \text{ where } g=k,$$

where  $\lambda$  can be any scalar. In words,  $\nabla f \parallel \nabla g$  because if not, there is a component of  $\nabla f$  that is  $\perp$  to  $\nabla g$  and therefore  $f$  can increase if traveled along  $g$ , until  $\nabla f \parallel \nabla g$ . In other words, the level sets must be  $\parallel$  (tangent) to  $g$  at solution point. [Given 2 constraints  $g=k, h=c$ , set  $\nabla f = \lambda \nabla g + \mu \nabla h$ ]

Multiple Integrals

Fubini's Thm: For a bounded continuous function  $f(x,y)$  on region  $E$ ,  $\iint_E f(x,y) dx dy = \iint_E f(x,y) dy dx$  whenever both integrals exist.

mass of region solid =  $m = \iiint_E \rho(x,y,z) dV$

average of  $f$  on  $E = \langle f \rangle = \frac{1}{m} \iiint_E f(x,y,z) \rho(x,y,z) dV$

For example, average value of  $f(x,y,z) = x$  gives  $x$ -coordinate of center of mass  $\bar{x} = \frac{1}{m} \iiint_E x \rho dV$

Finding bounds of integration can either be done geometrically or analytically using inequalities.

Change of Variables

When changing variables from one coordinate system  $(x,y,z) \rightarrow (u,v,w)$ , the integrand must be multiplied by a magnification factor: the absolute value of the

Jacobian:  $\left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| = \begin{vmatrix} \partial x/\partial u & \partial x/\partial v & \partial x/\partial w \\ \partial y/\partial u & \partial y/\partial v & \partial y/\partial w \\ \partial z/\partial u & \partial z/\partial v & \partial z/\partial w \end{vmatrix} = \left| \frac{\partial(u,v,w)}{\partial(x,y,z)} \right|^{-1}$

Ex. for polar coordinates  $dA = r dr d\theta$ ; cylindrical,  $dV = r dr d\theta dz$ ; spherical,  $dV = r^2 \sin \phi dr d\phi d\theta$

Vector Fields and Line Integrals

To integrate a function  $f$  in  $\mathbb{R}$  over a curve  $C$ , to produce the "area under the fence" or "mass" of  $C$  if  $f$  is interpreted as mass density, parametrize  $C$  into

$\vec{r}(t) = \langle x(t), y(t) \rangle$ , where  $a \leq t \leq b$ , and compute  $\int_C f(x,y) ds = \int_a^b f(\vec{r}(t)) |\vec{r}'(t)| dt$ , where

$|\vec{r}'(t)| = \sqrt{(dx/dt)^2 + (dy/dt)^2}$ .  $\int_C$  wrt  $x = \int_a^b f(x,y) dx = \int_a^b f(\vec{r}(t)) x'(t) dt$

A line integral of a vector field  $\vec{F}$  along curve  $C = \int_C \vec{F} \cdot d\vec{r}$  If  $\vec{F}$  is a force, this gives work.

$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F} \cdot \vec{r}'(t) dt$

Fundamental Thm of Line Integrals gives  $\int_C \vec{F} \cdot d\vec{r} = f(\vec{r}(b)) - f(\vec{r}(a))$  given  $\vec{F}$  is conservative

$\{\vec{F} \text{ is conservative}\} = \{\text{there exists a potential } f \text{ such that } \vec{F} = \nabla f\} = \{\int_C \text{ is path-independent}\} = \{\text{if } \vec{F} = \langle P(x,y), Q(x,y) \rangle, \frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}\} = \{\int_C \vec{F} \cdot d\vec{r} = \phi \text{ for every closed path } C \text{ in } D\}$